

Open Hardware for the Ocean

Protei

The Exploratorium

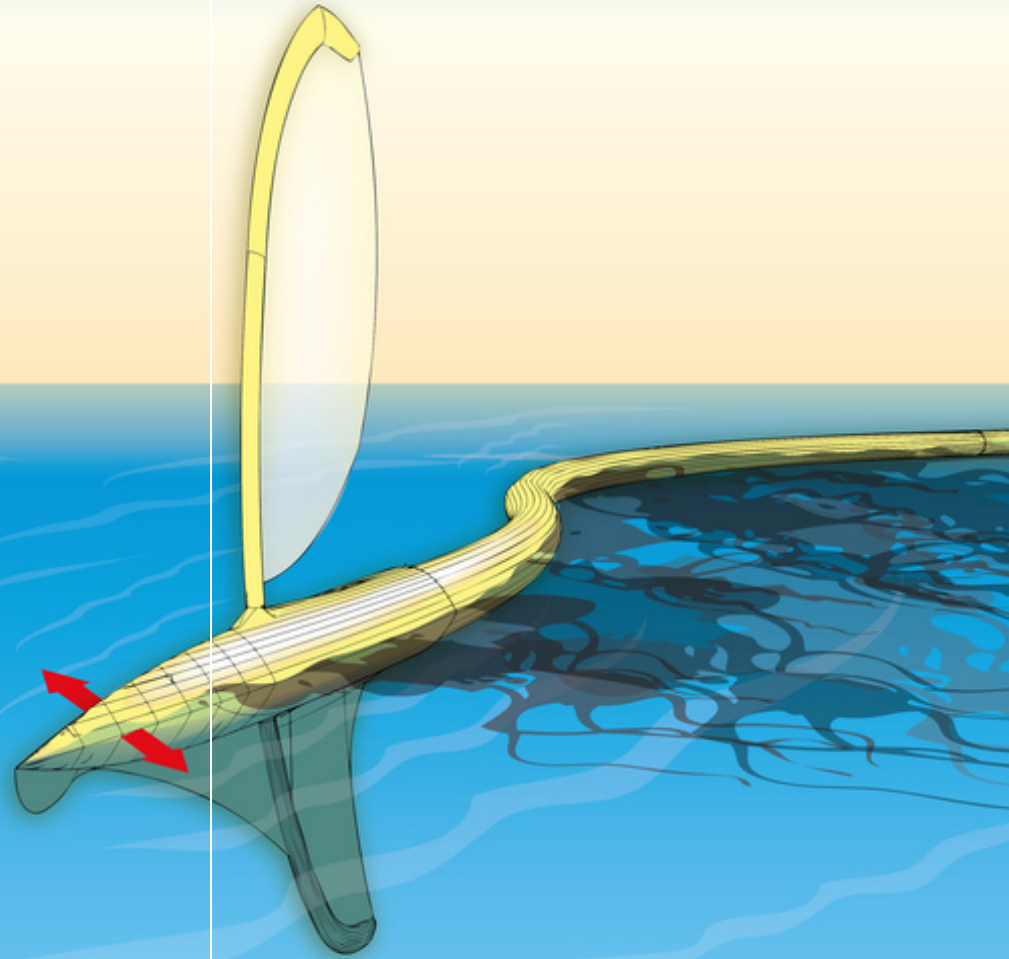
<http://protei.org>

Cesar Harada

contact@protei.org

Gabriella Levine

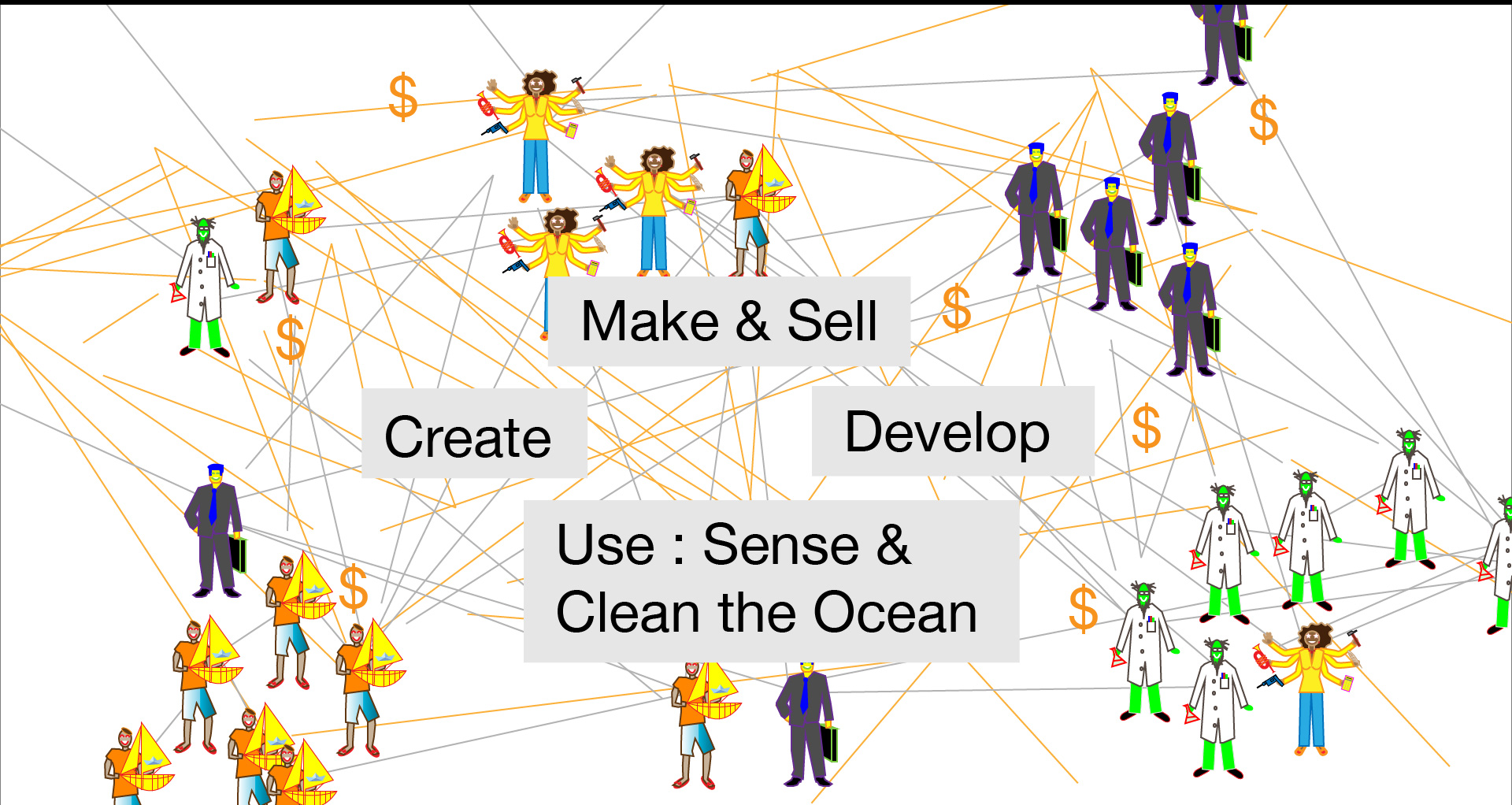
gabriella@opensailing.net



Open-H₂O







Innovation Network



Competition => Collaboration

Product => Market

<p>Object, mechanical design</p>  <p>open hardware</p>	<p>Documentation, texts, photos, videos, communication materials</p> <p>Creative Commons BY-SA</p> 	<p>Source code</p> <p>GNU General Public License, version 3 (GPL-3.0)</p> 	<p>Name, trademark</p> <p>US trademark regulation #85339997</p> 
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Everyone is FREE to
Use
Modify
Distribute



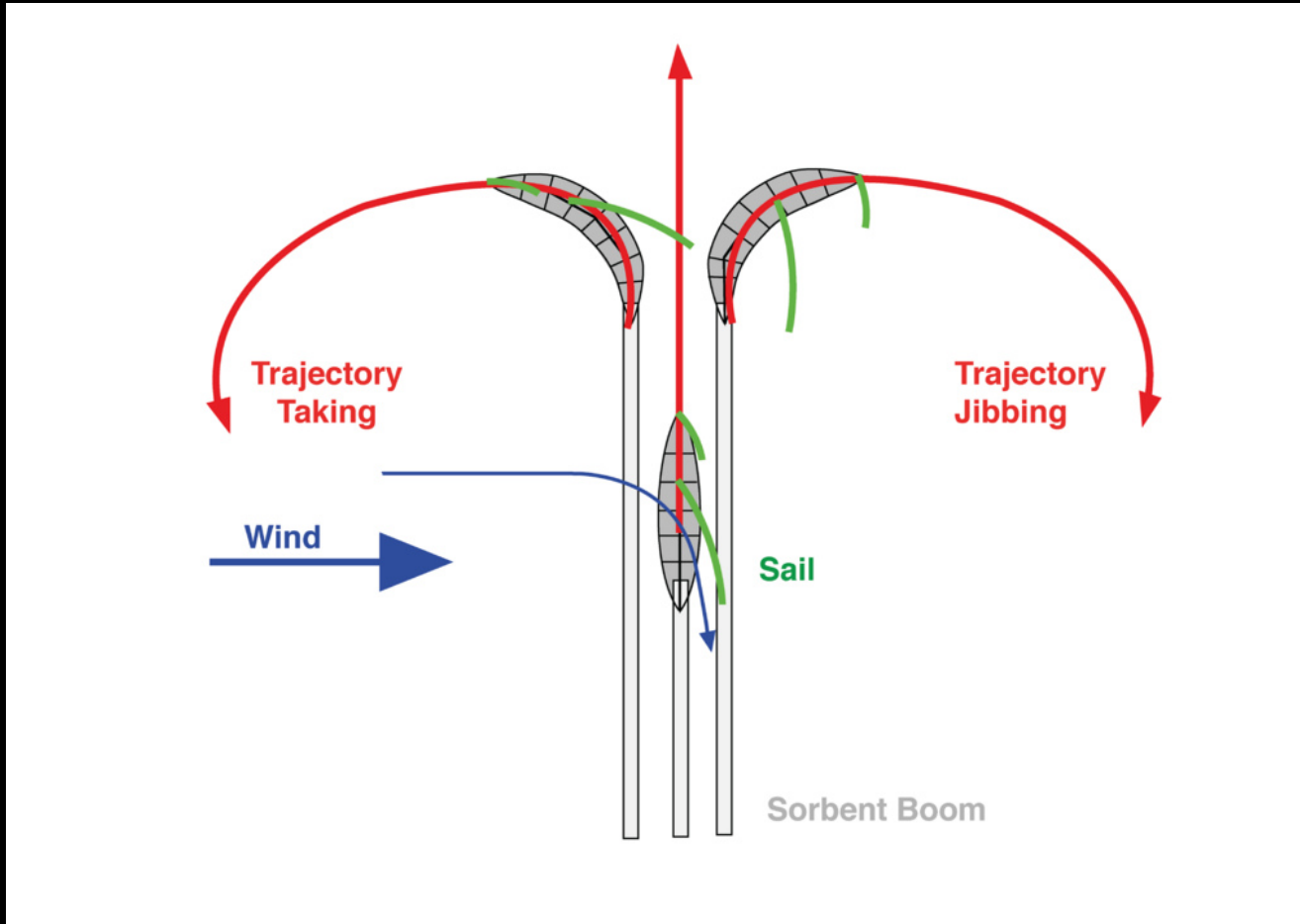
In exchange one must
Credit "Protei"
Share finding with community

Physics



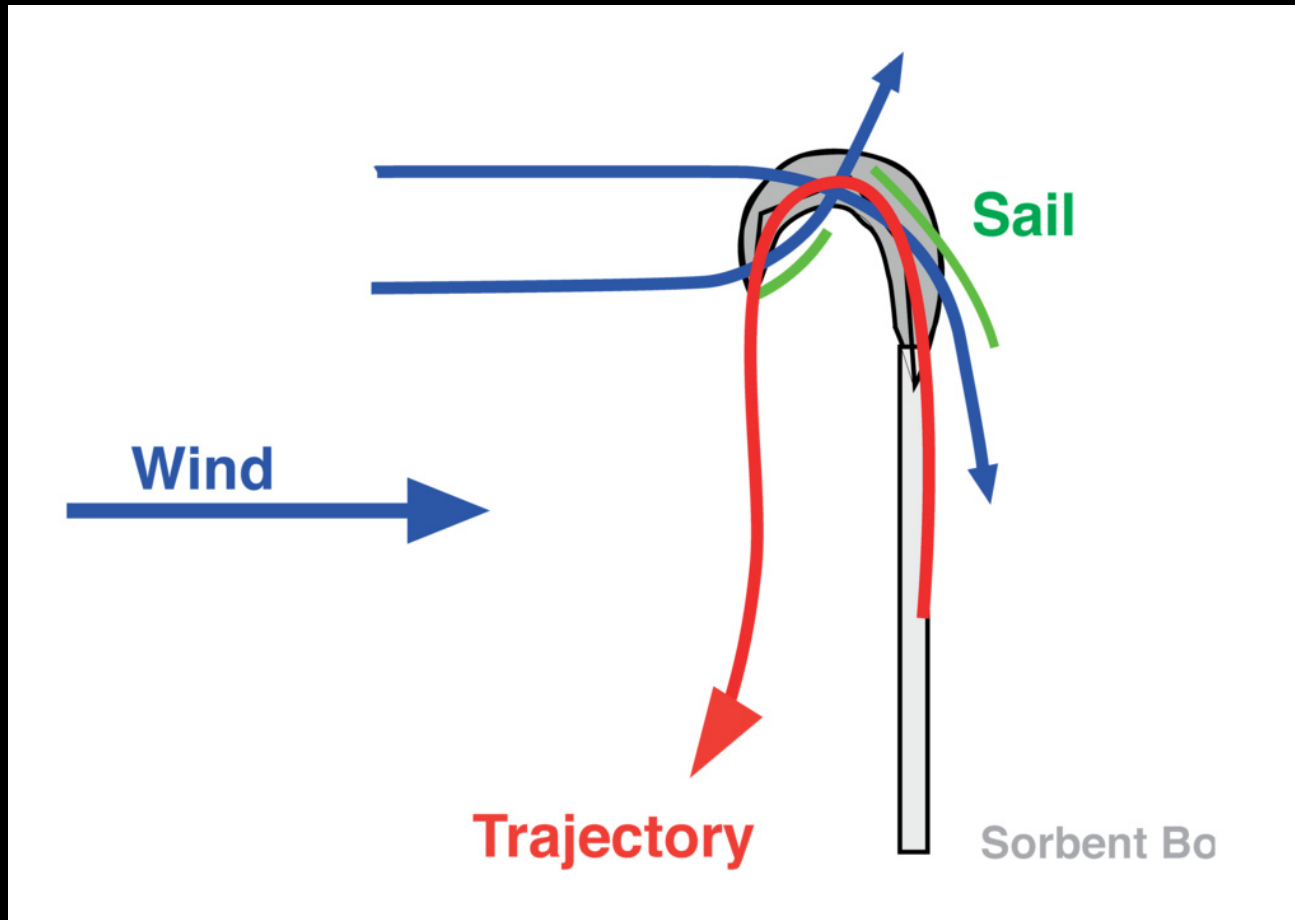
What are the new properties of a shape shifting hull?

Physics



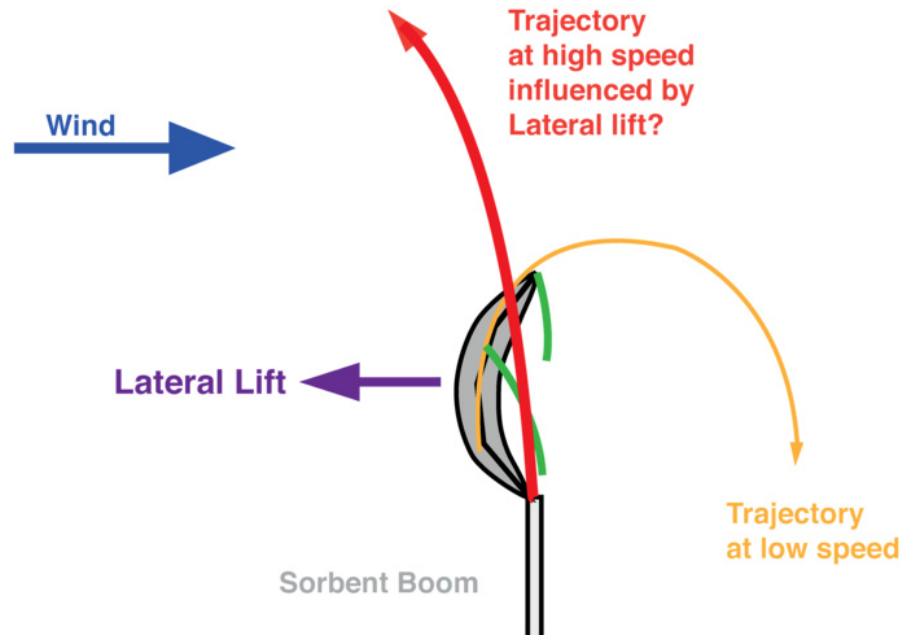
Can a shape-shifting hull improve trajectory control ?

Physics



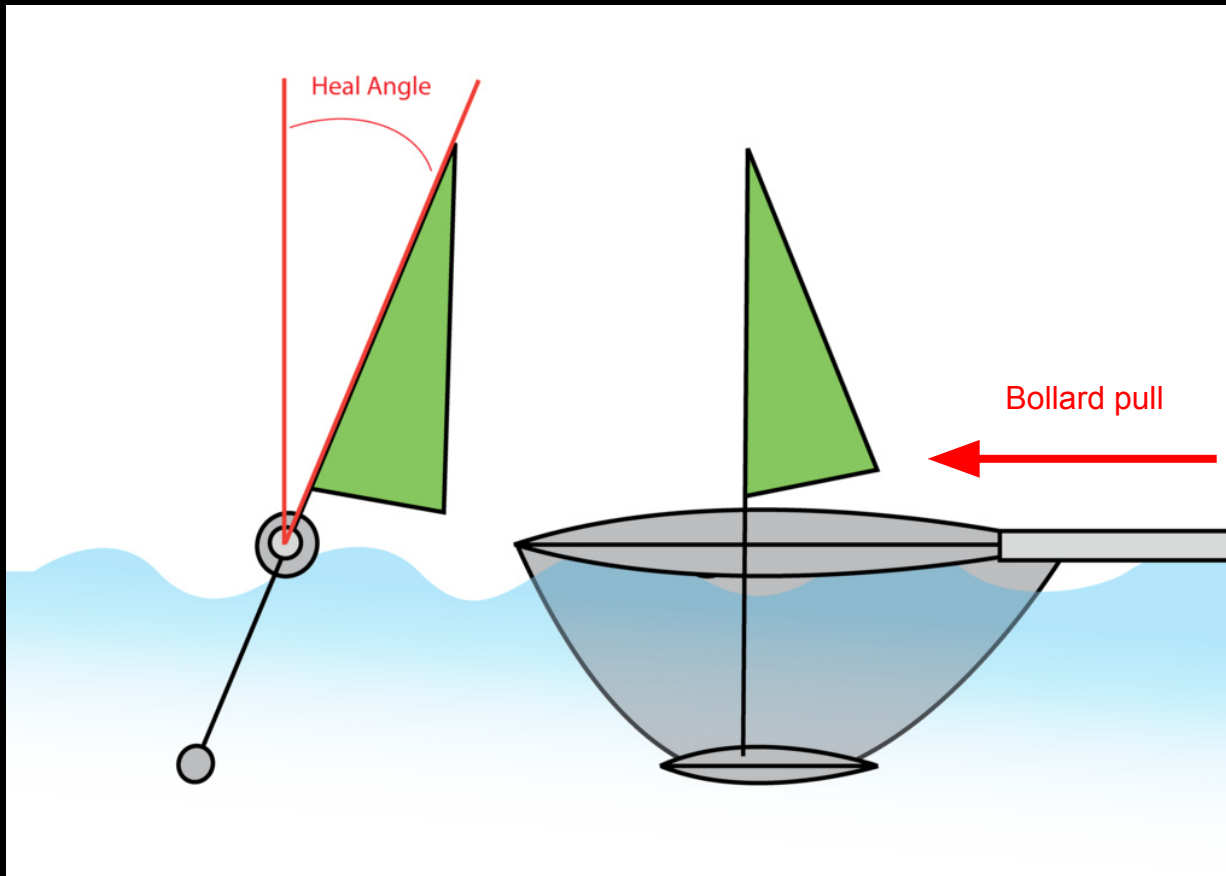
Can a shape-shifting hull improve help us tack and jibe more efficiently ?

Physics



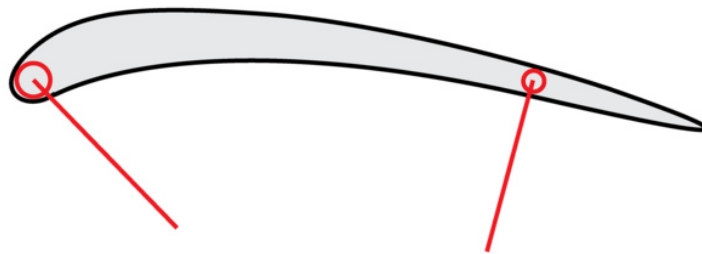
What curvature of hull would provide lateral lift and at what speed?

Physics

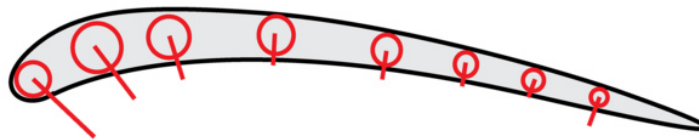


How to make Protei an efficient self-righting tugging vessel?
What is the Bollard pull of Protei ?

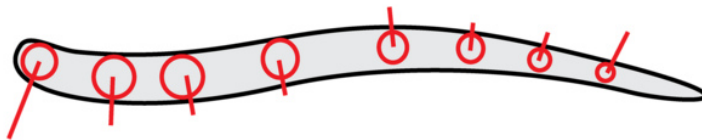
Physics



Few actuators on a surface.
A lot of energy on few motors.



Many actuators on a surface.
Little energy on each motors.

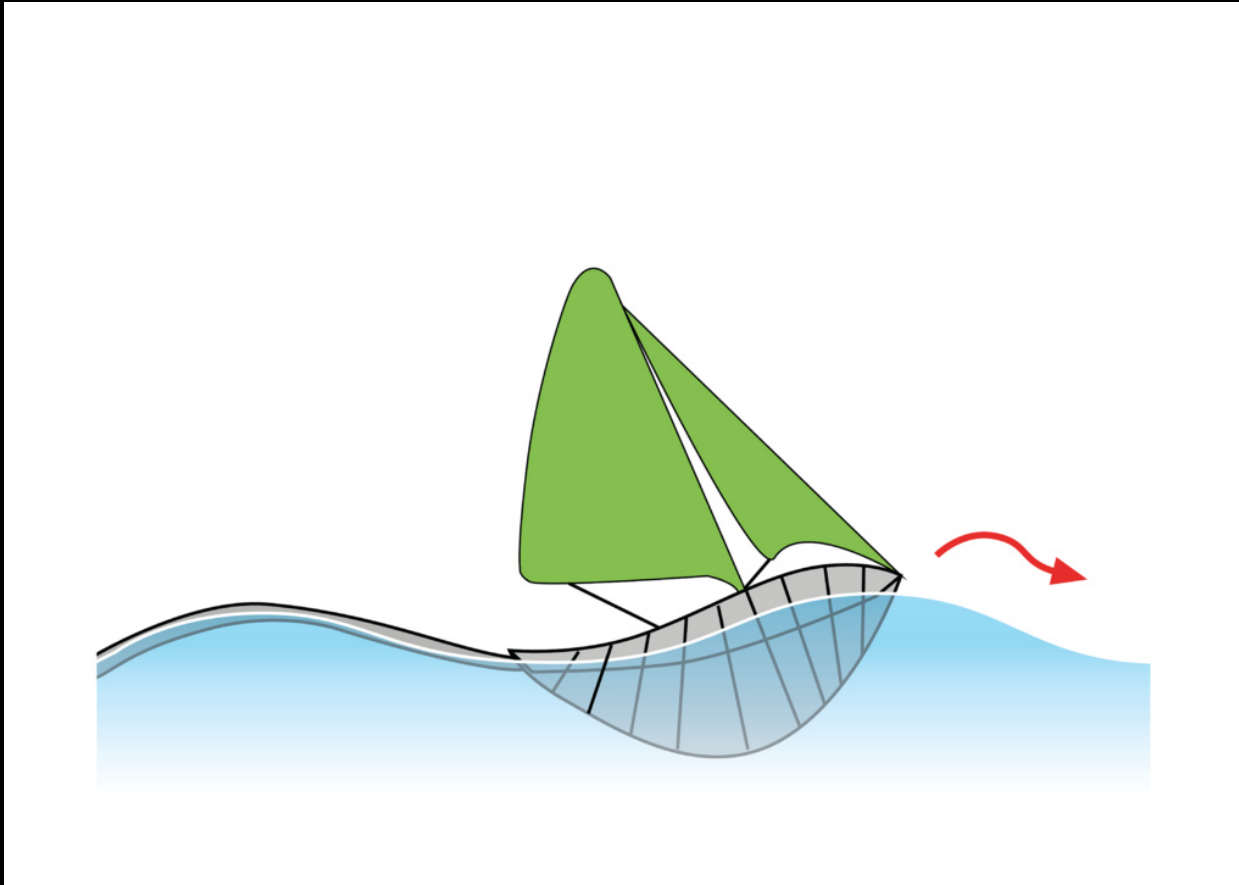


Many actuators on
a complex surface.
Complex control.

Can we actuate a large surface with many low power actuators, rather than a few high power actuators?

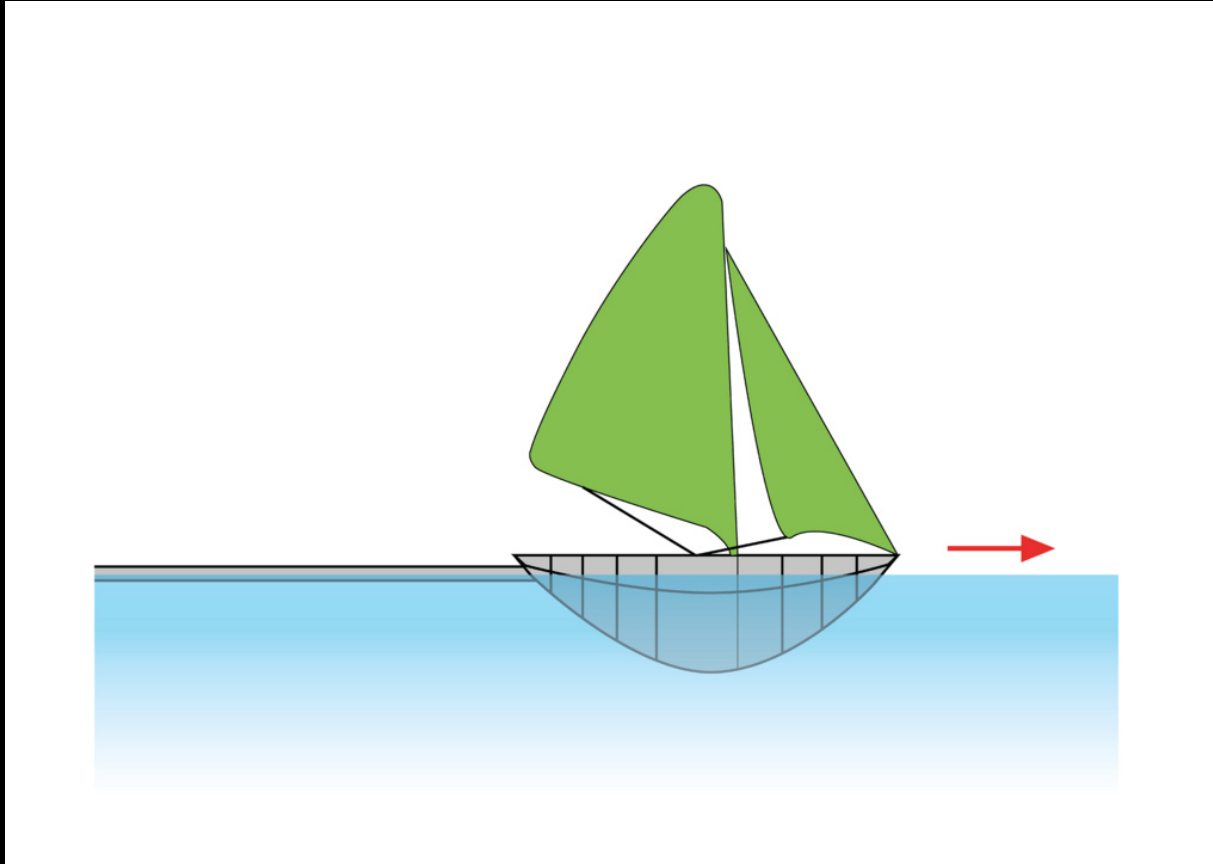
Can We achieve fine control of complex surfaces?

Physics



Can environmental noise be absorbed by our flexible hull, allowing more forward motion ?

Physics



Without no keel and no rudder, can we produce less resistance, less turbulence, less stern wave?

COMMUNICATION

1. Radio (250 m)
2. GSM (cell / sim card)
3. Global reception: Satellites



RADIO



CELL

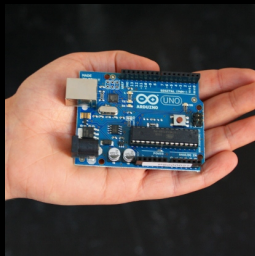


SATELLITE



DISTANCE (RANGE)

COMPUTATIONAL ARCHITECTURE



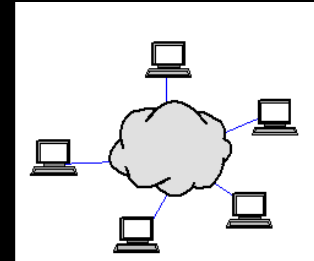
Arduino



BeagleBone (Linux)



Android

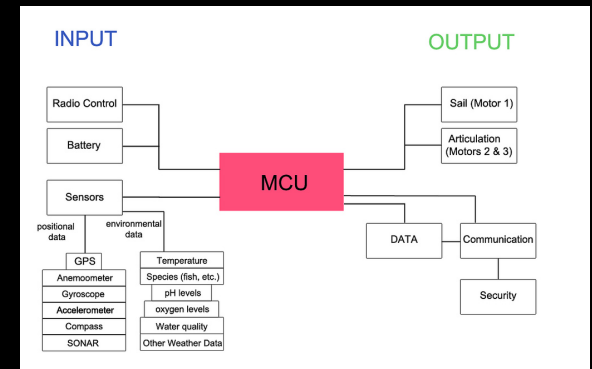
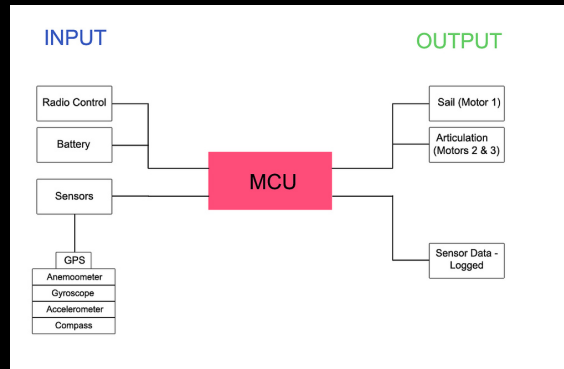
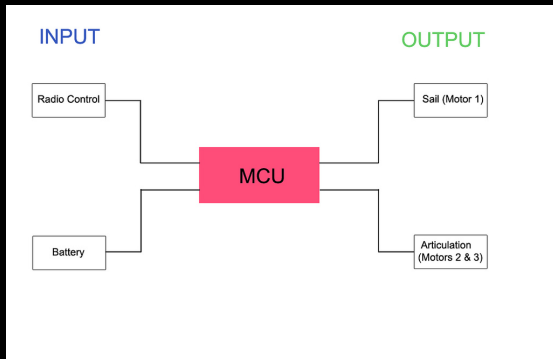


Cloud



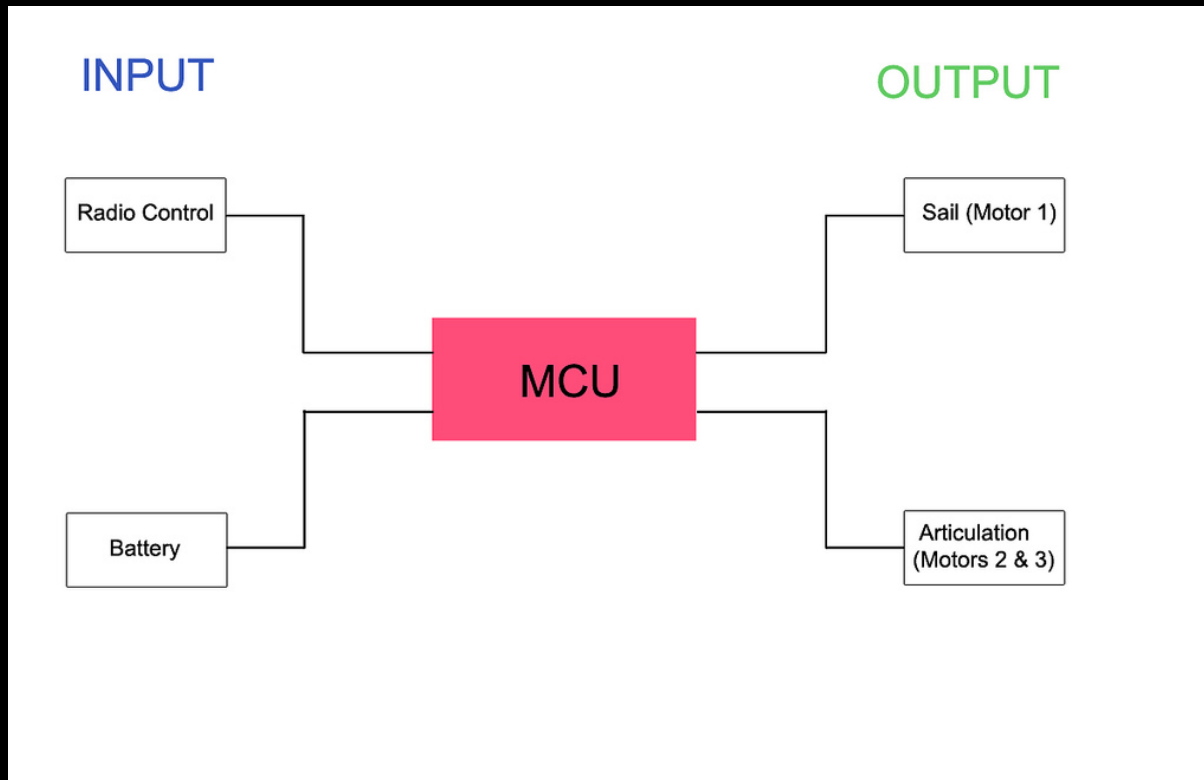
COMPLEXITY

ELECTRONIC STRUCTURE



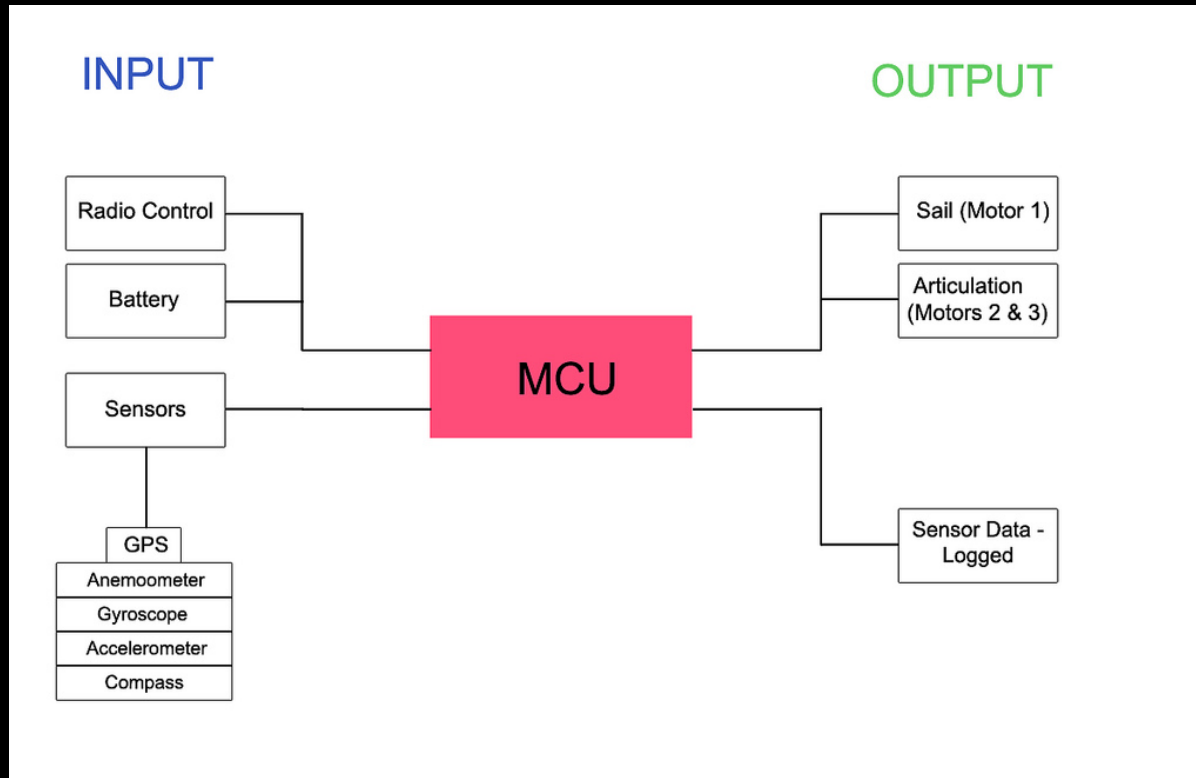
COMPLEXITY

ELECTRONIC STRUCTURE



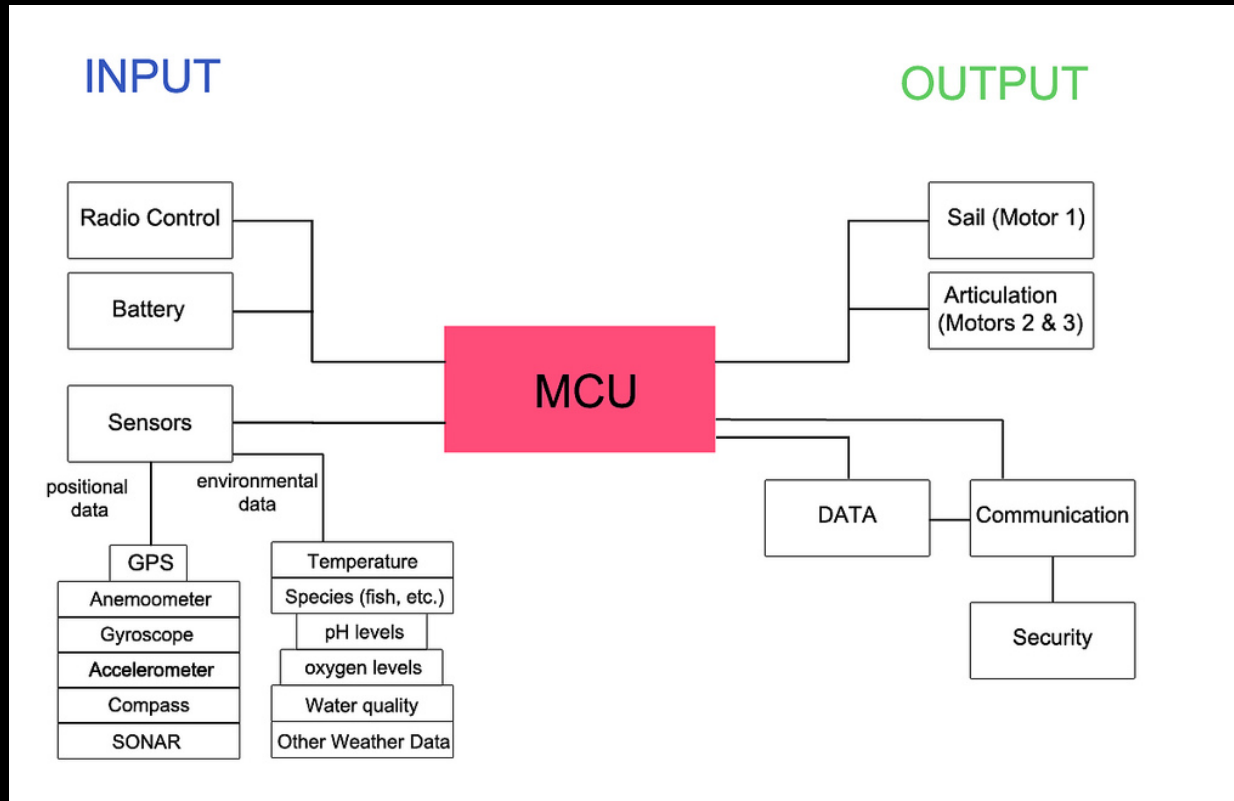
-user controlled

ELECTRONIC STRUCTURE



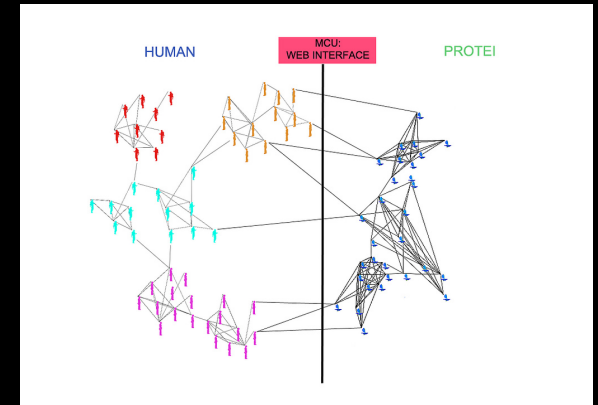
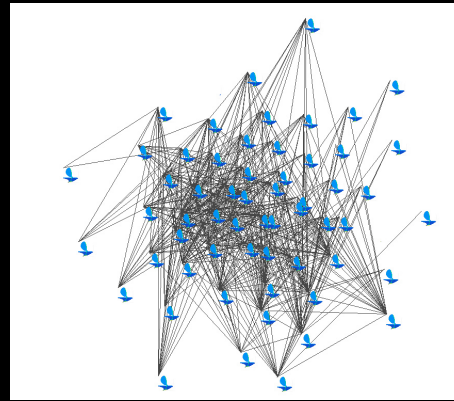
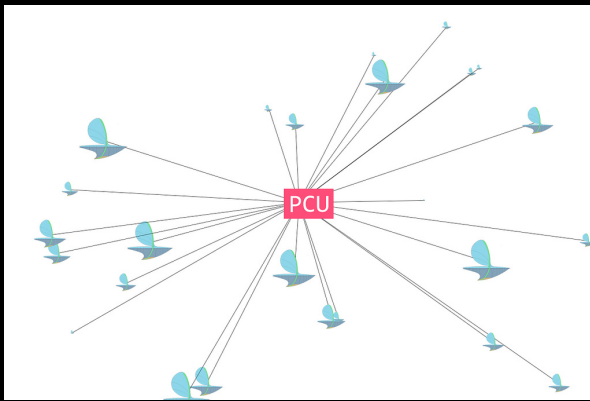
- positional sensors for feedback

ELECTRONIC STRUCTURE



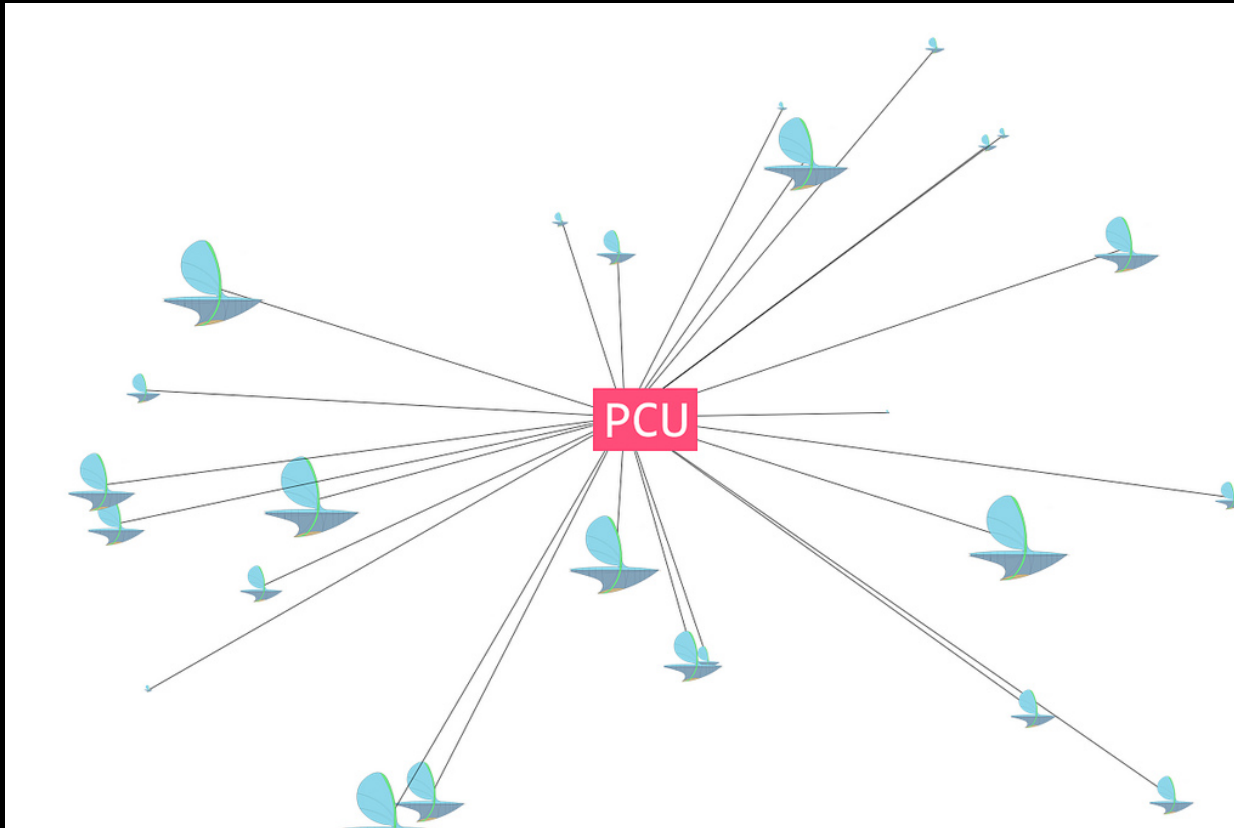
- environmental sensors
- positional sensors

NETWORK STRUCTURE



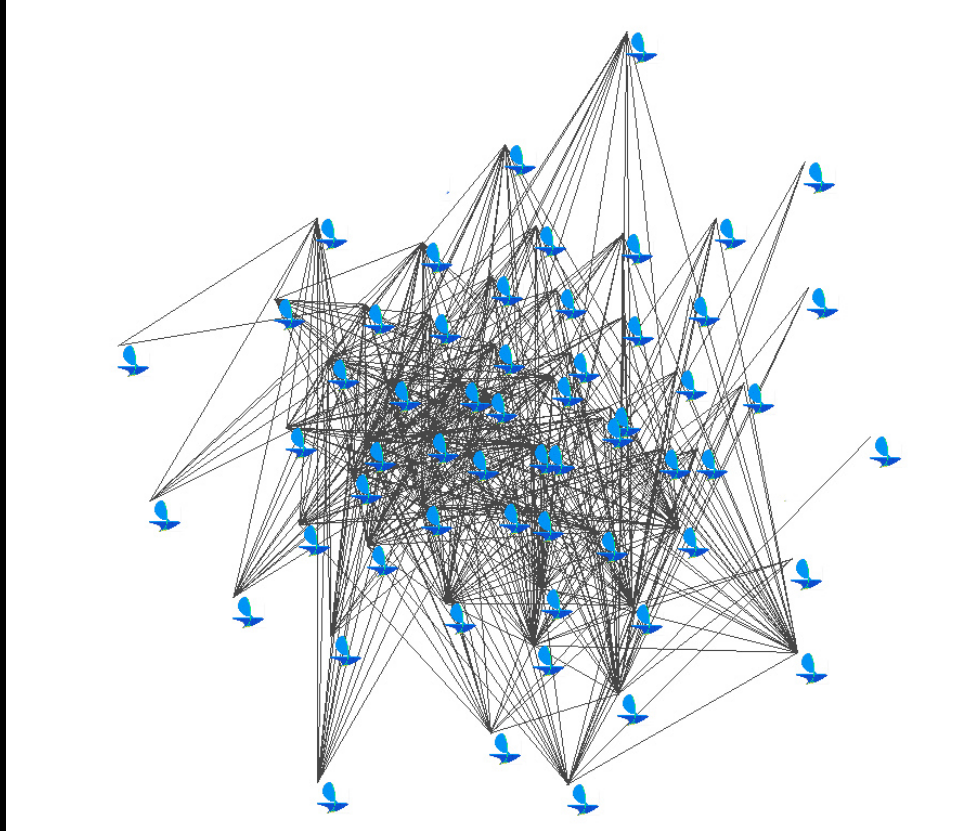
COMPLEXITY

NETWORK STRUCTURE



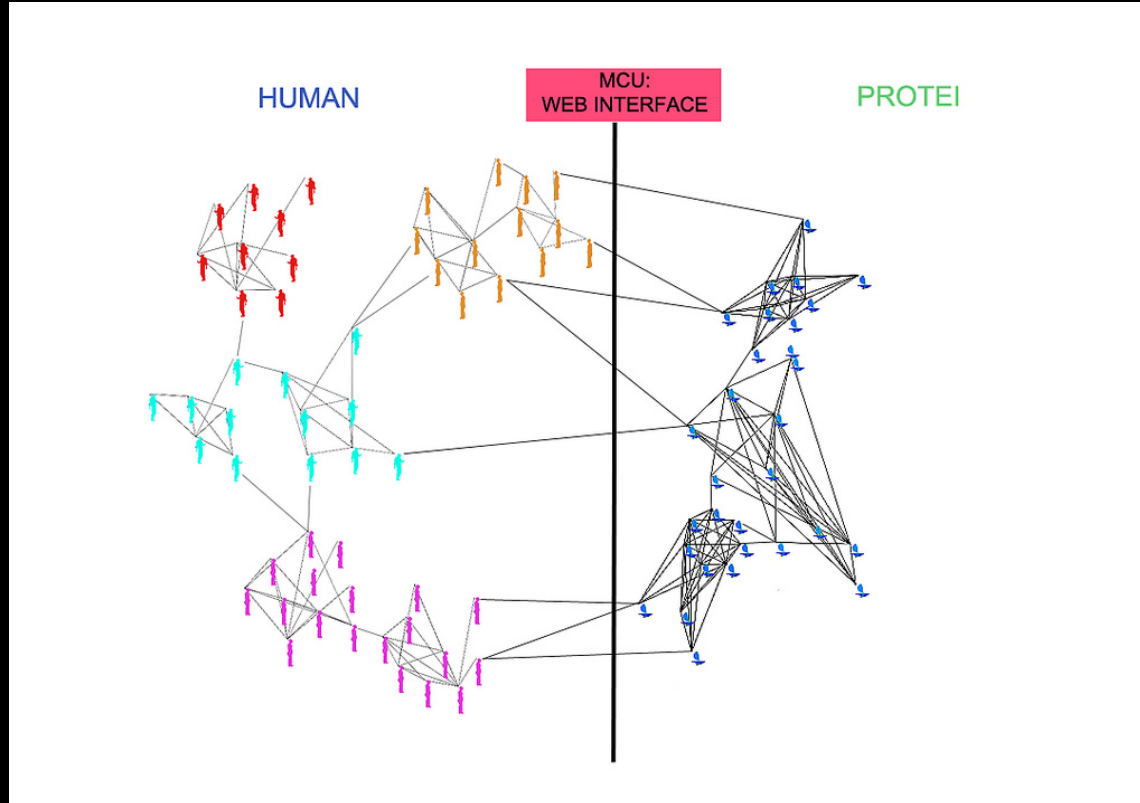
- Swarm of boats
- Centralized control

NETWORK STRUCTURE



- Swarm of boats
- decentralized control

NETWORK STRUCTURE



- Swarm of boats
- Web Interface
- Networked communication

WEB INTERFACE

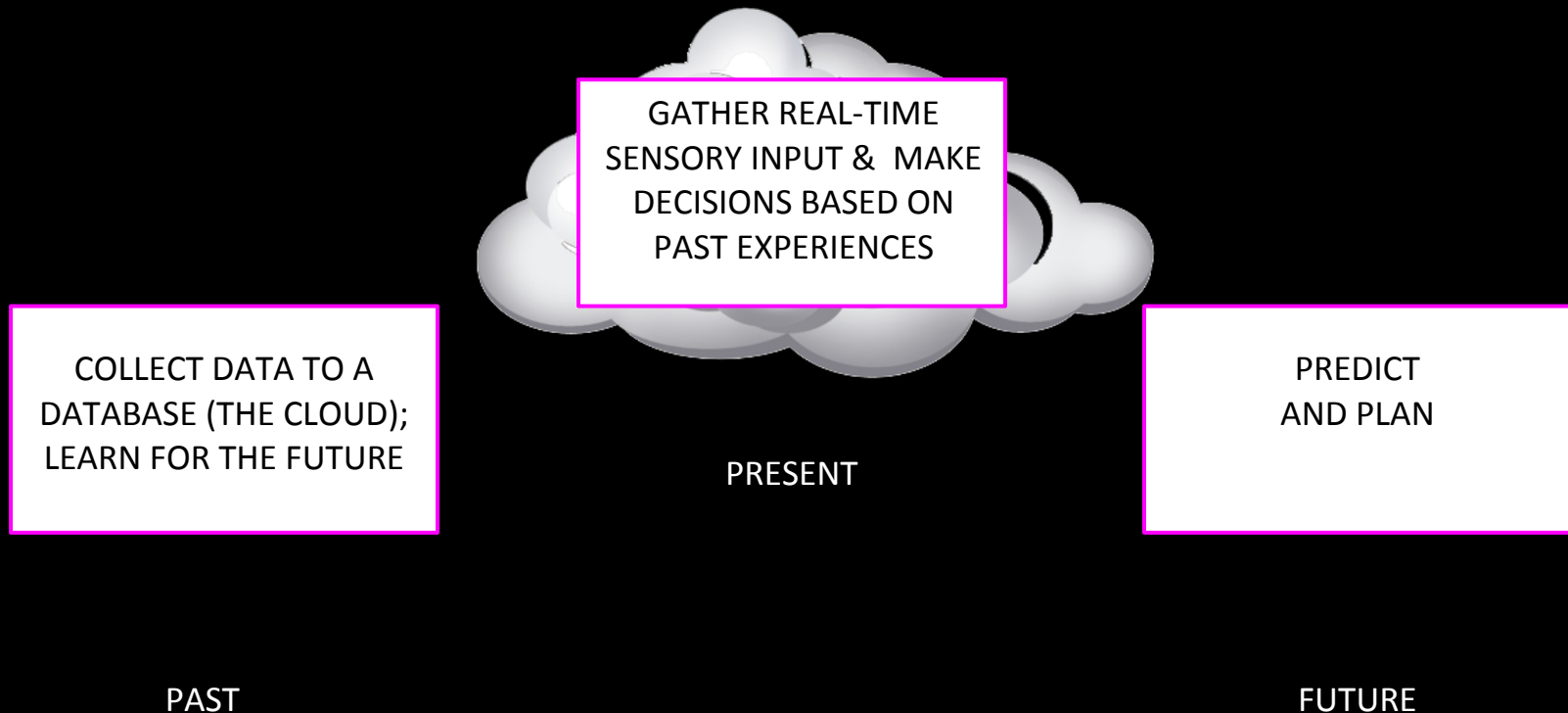


- Multi-platform network
- onshore gamers, fishermen

GAMING INTERFACE



ARTIFICIAL INTELLIGENCE



- Communication between units
- Logging and learning from feedback and forecasting

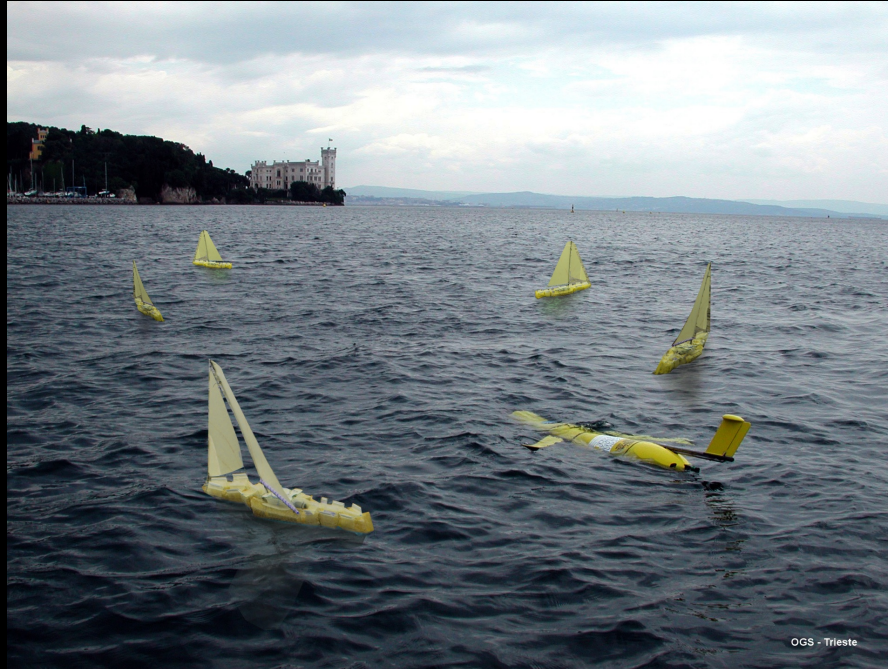
2012: 1m Remote Controlled



USERS: hobbyists, kids, hackers

FUNCTION: data collection, toys, education, platform for further research and development

2013: 1m Autonomous



USERS: scientists, engineers

FUNCTION: marine data collection, oceanography, coordination with underwater vehicles, toxicity level measurements, fishery monitoring

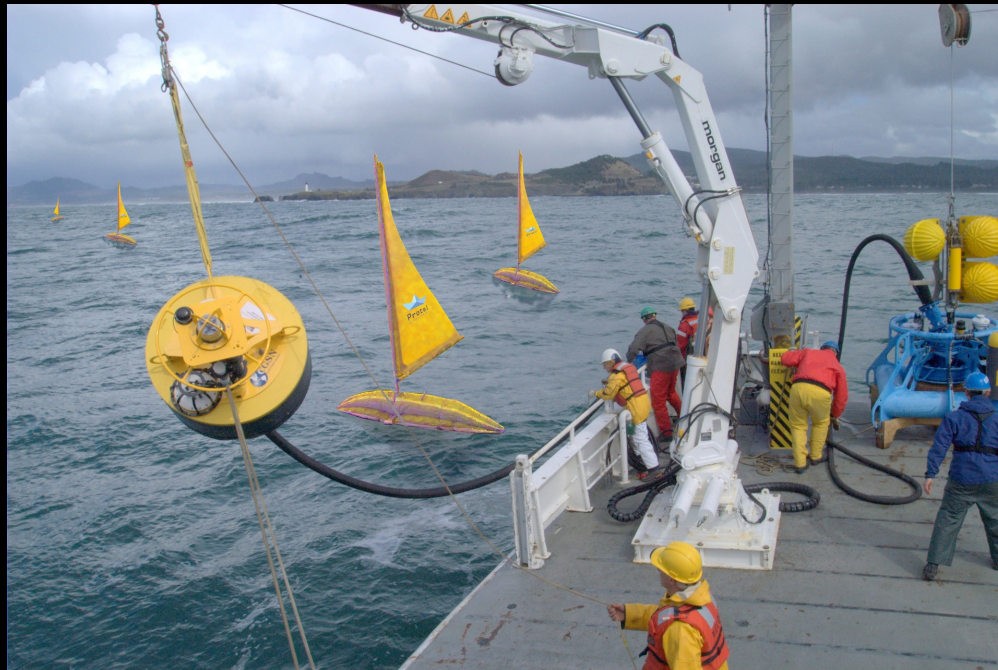
2014: 6m Manned



USERS: sailors

FUNCTION: test the new technology of high performance flexible hulls

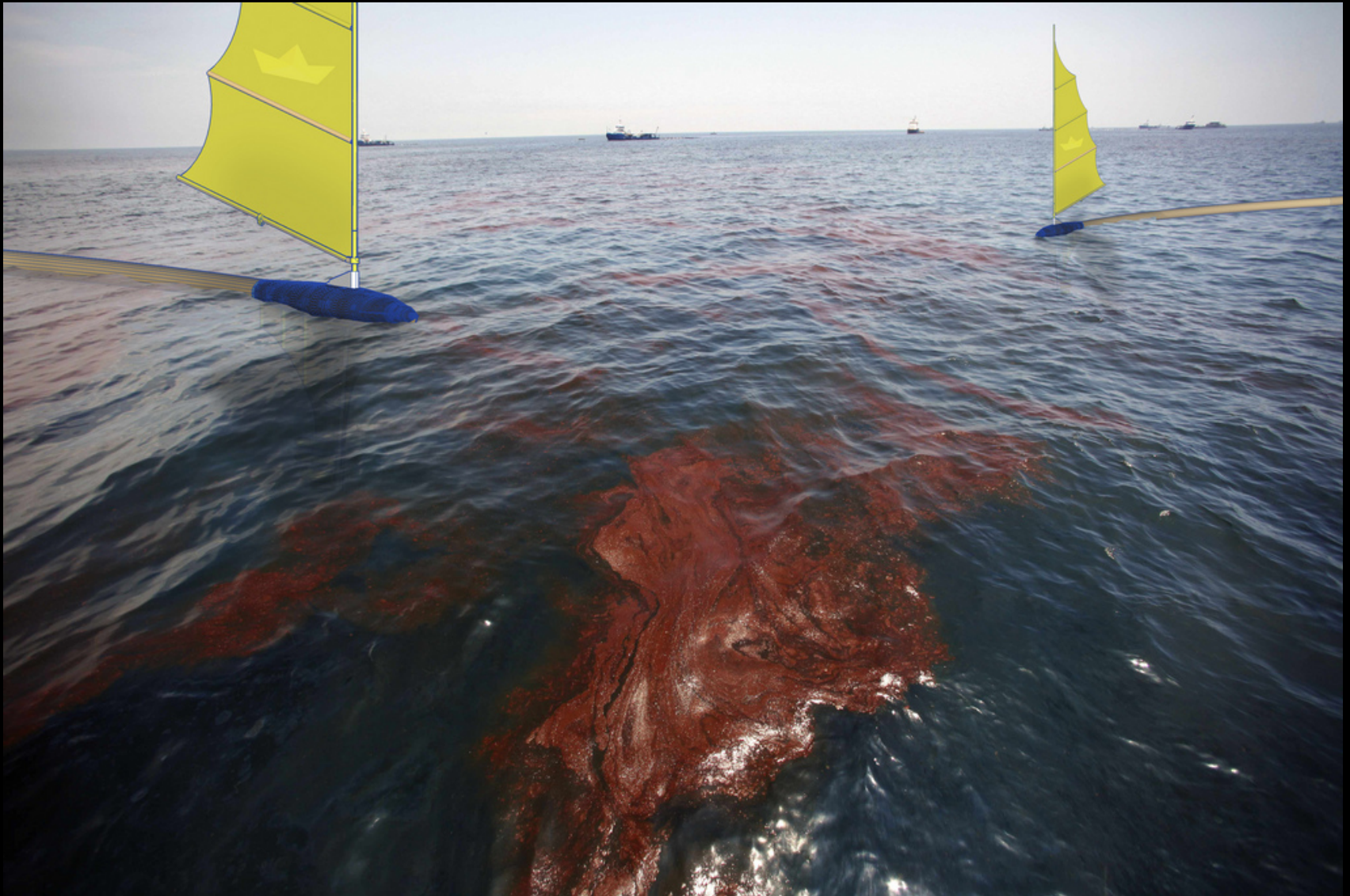
2015: 6m Autonomous



USERS: activists, environmentalists, governments, teachers, scientists, engineers

FUNCTION: ocean sensing, ocean cleaning, carry heavy payloads

APPLICATIONS: Oil Collection



APPLICATIONS: Plastic Trash Collection



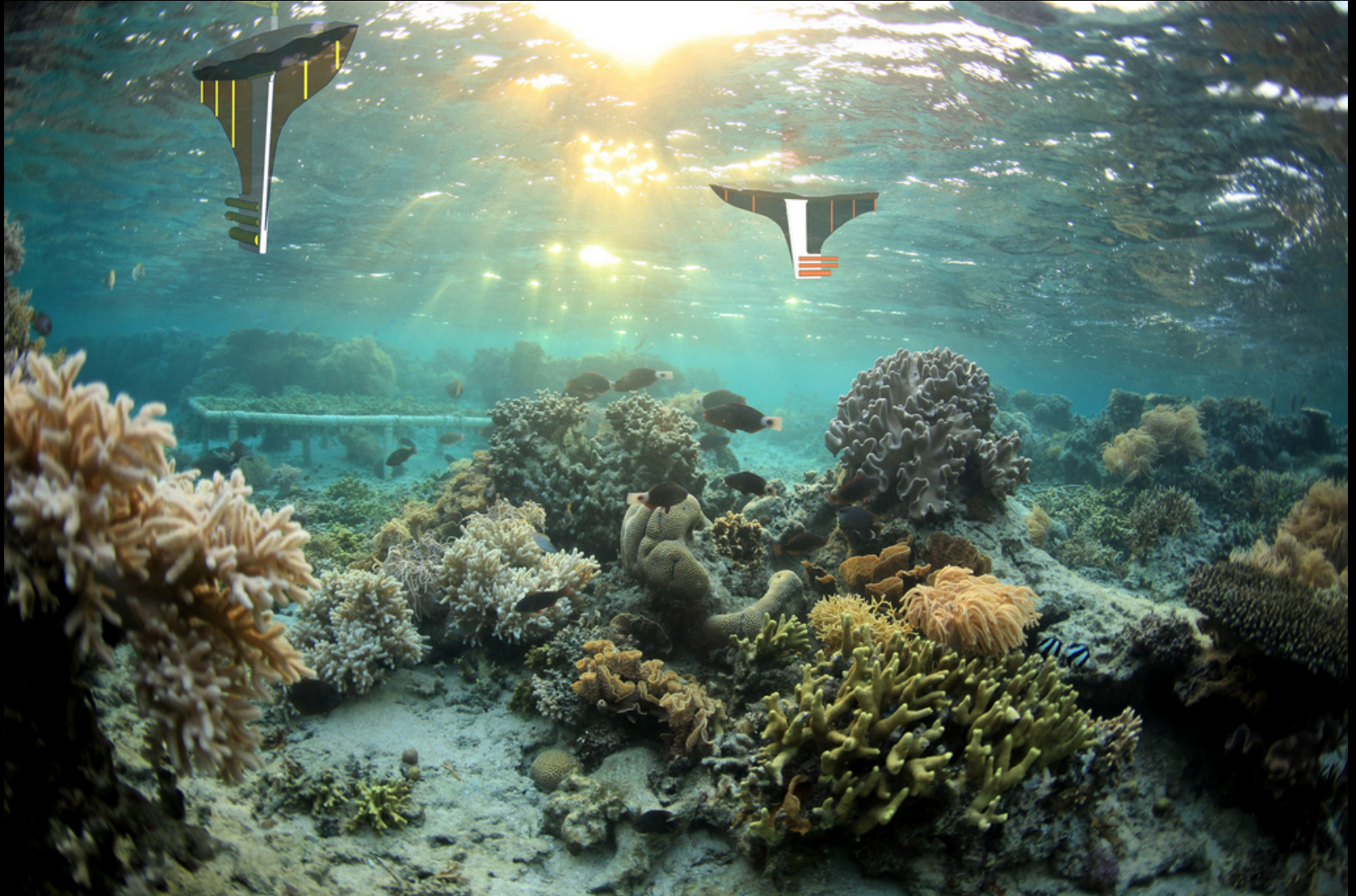
APPLICATIONS: Fishery Monitoring



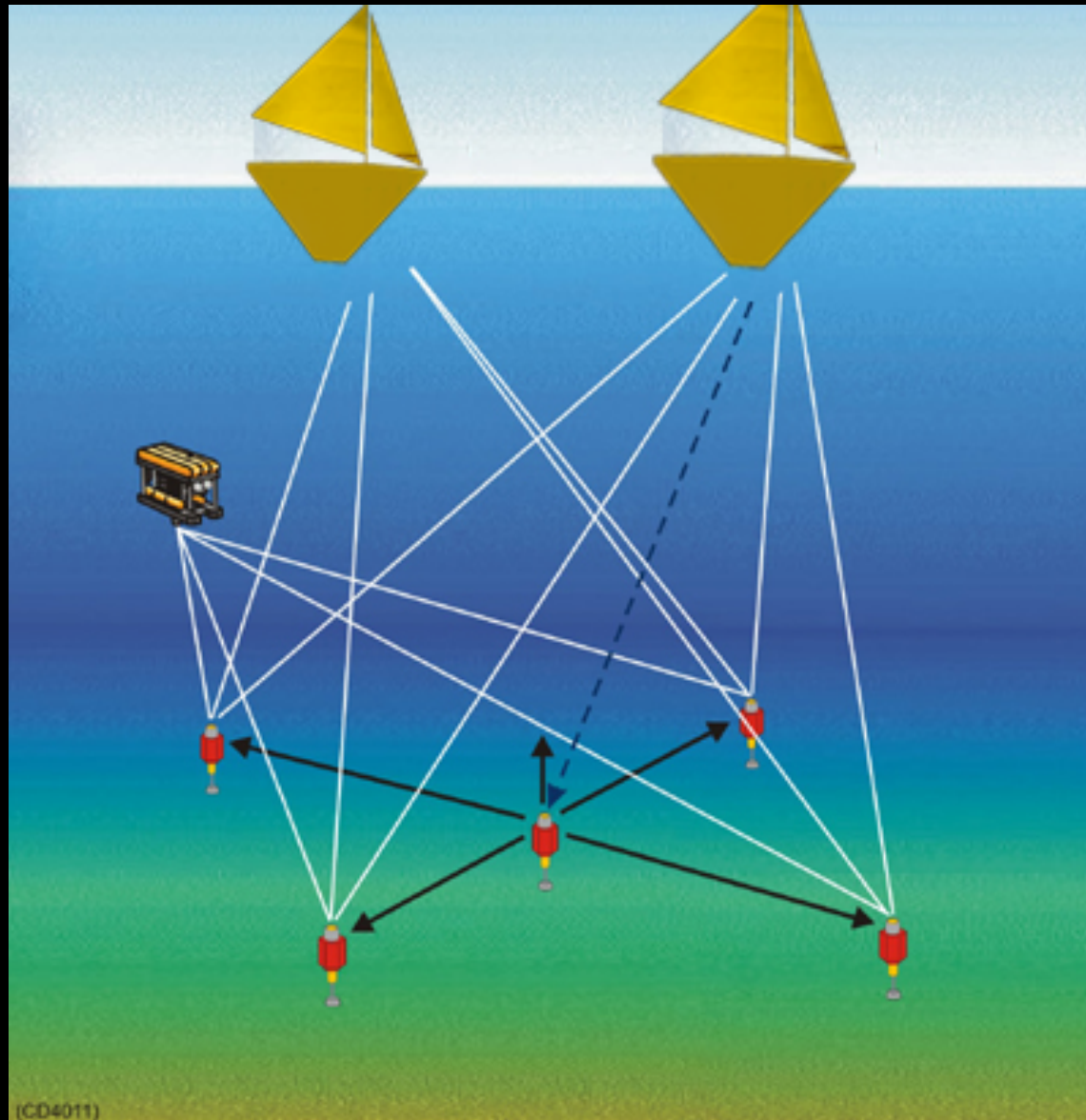
APPLICATIONS: Algal Blooms



APPLICATIONS: Coral Reef Mapping



APPLICATIONS: Subsurface Communication



APPLICATIONS: Astroparticle Physics



Protei + Exploratorium



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Protei

at the Exploratorium, San Francisco 20120814

<http://protei.org>

Cesar Harada

contact@protei.org

Gabriella Levine

gabriella@opensailing.net

